PPSN 2016

Tutorial on Evolutionary Multiobjective Optimization

Dimo Brockhoff

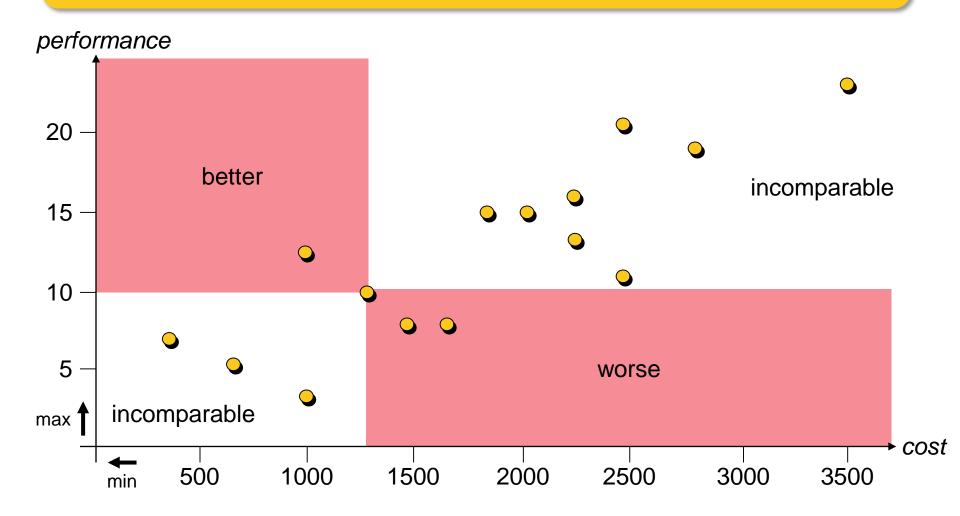
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updated slides will be available at http://researchers.lille.inria.fr/~brockhof/

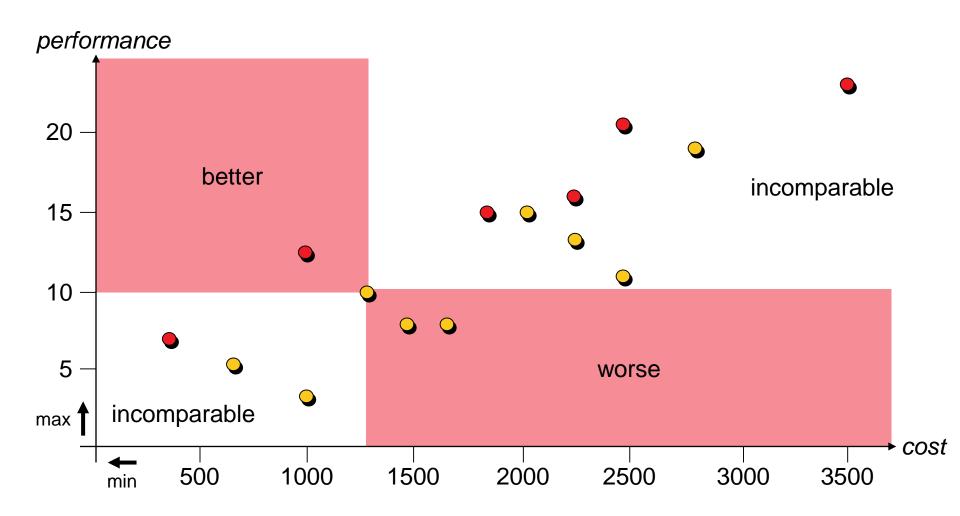


Multiobjective Optimization

Multiple objectives that have to be optimized simultaneously

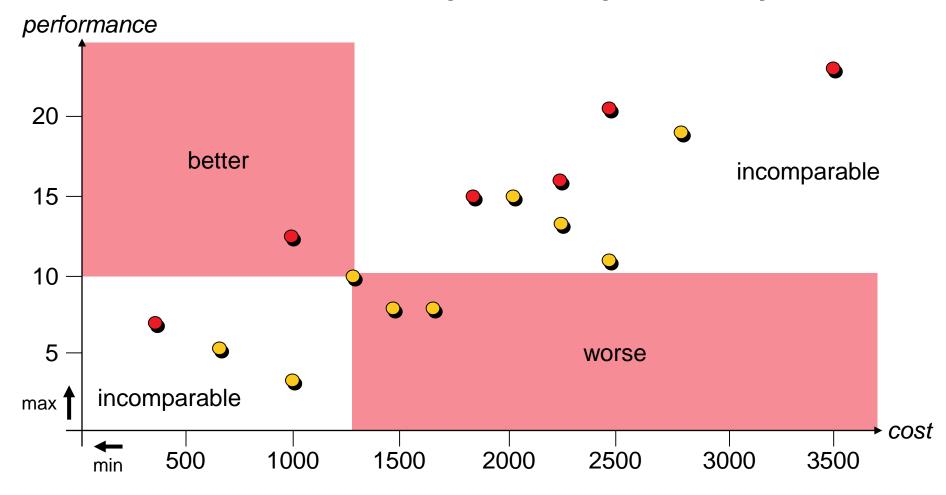


- Observations: there is no single optimal solution, but
 - 2 some solutions (•) are better than others (•)



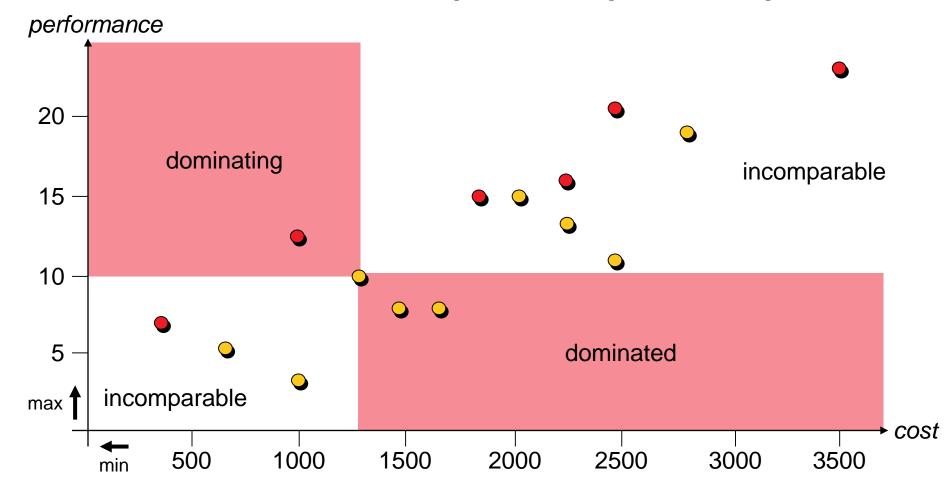
u weakly Pareto dominates v ($u \leq_{par} v$): $\forall 1 \leq i \leq k : f_i(u) \leq f_i(v)$

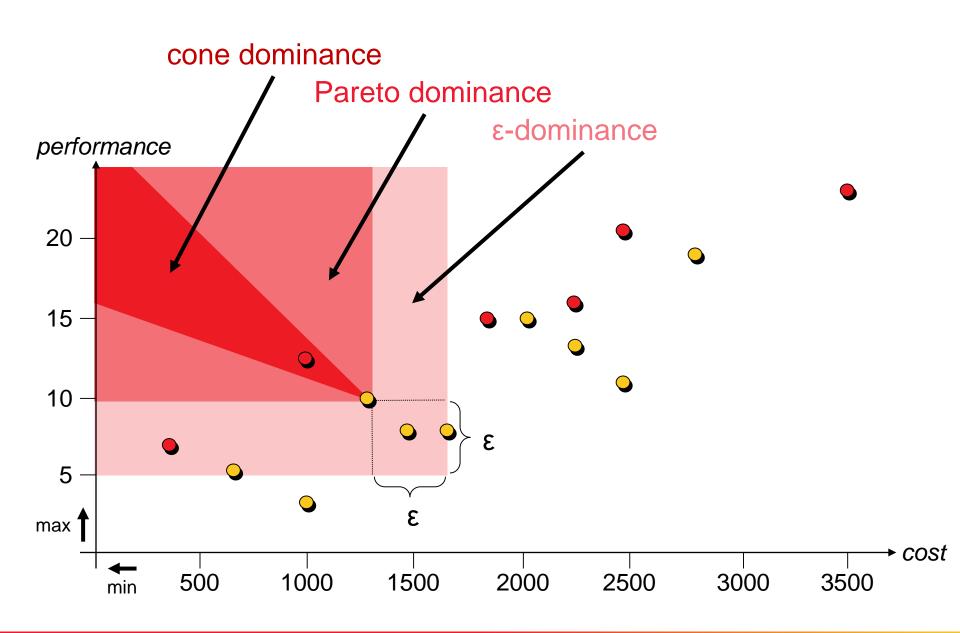
 $u \ Pareto \ dominates \ v \ (u <_{par} v): \ u \leqslant_{par} v \land v \not\leqslant_{par} u$



u weakly Pareto dominates v ($u \leq_{par} v$): $\forall 1 \leq i \leq k : f_i(u) \leq f_i(v)$

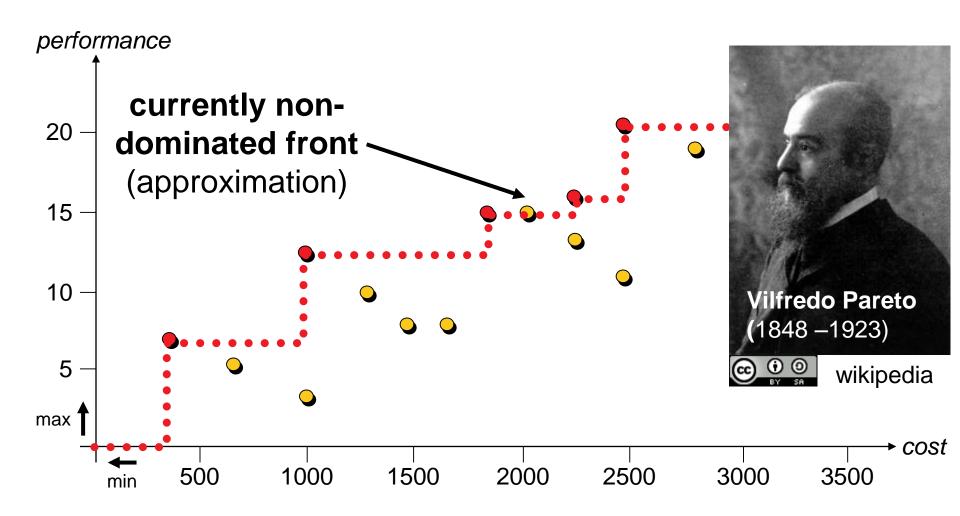
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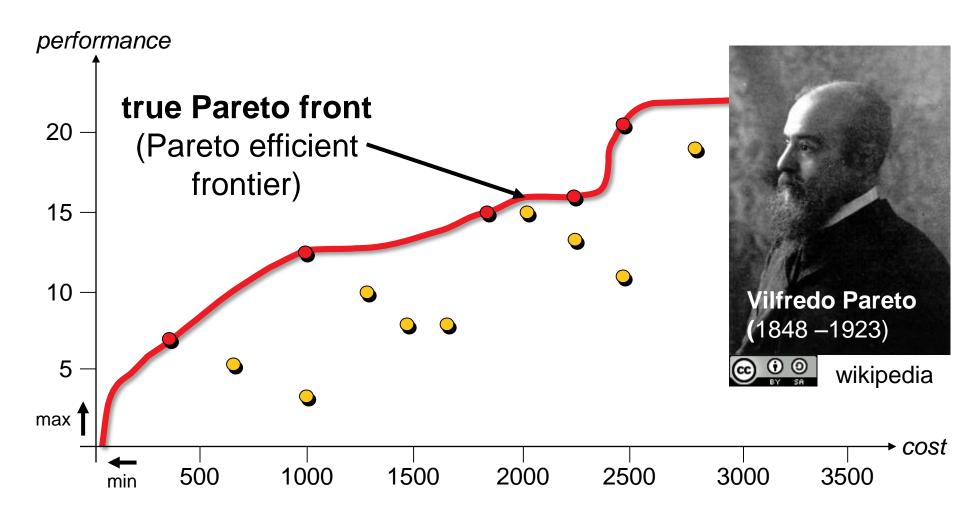
Pareto set: set of all non-dominated solutions (decision space)

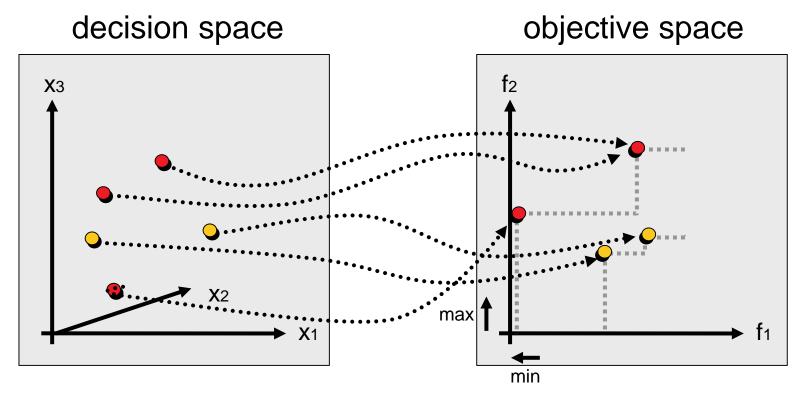
Pareto front: its image in the objective space



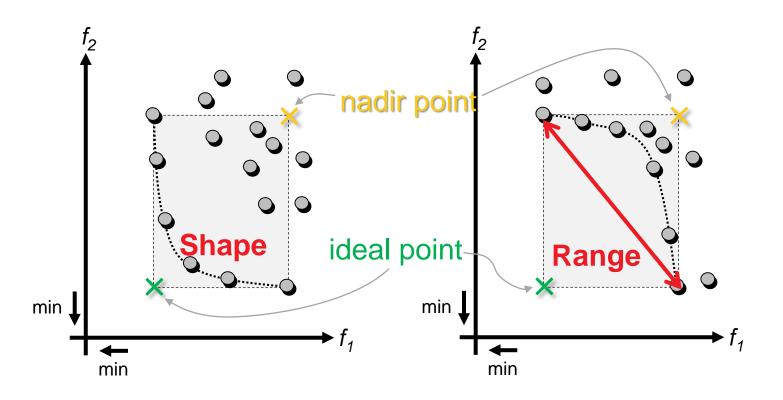
Pareto set: set of all non-dominated solutions (decision space)

Pareto front: its image in the objective space





- solution of Pareto-optimal set non-optimal decision vector
- vector of Pareto-optimal front non-optimal objective vector



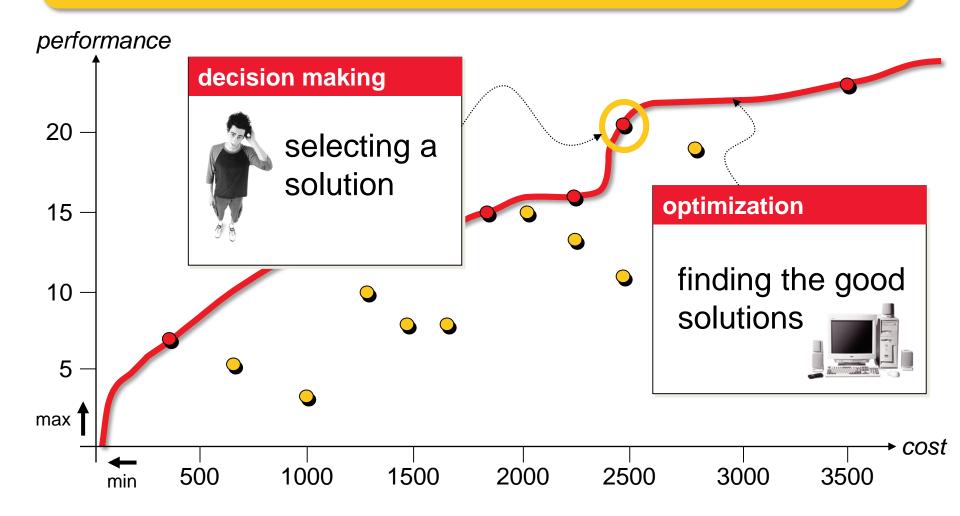
ideal point: best values nadir point: worst values

obtained for *Pareto-optimal* points

Optimization vs. Decision Making

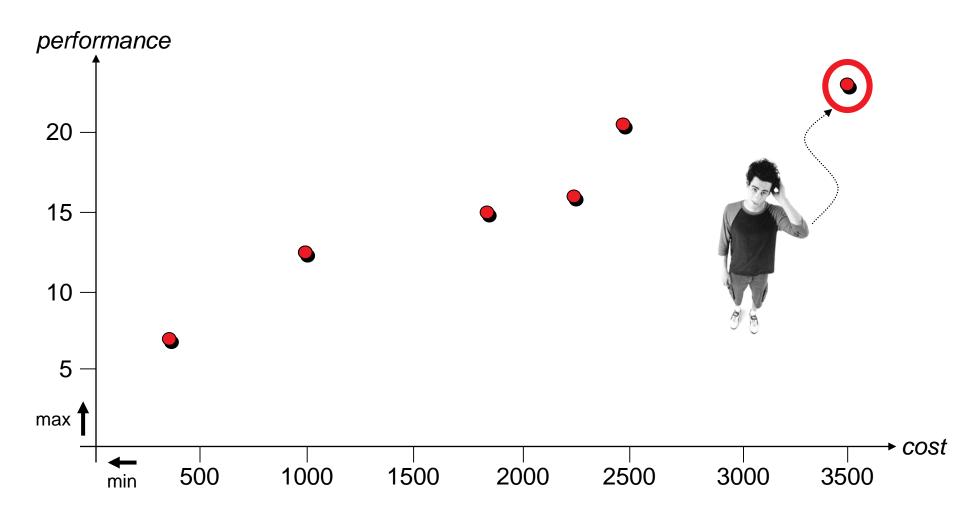
Multiobjective Optimization

combination of optimization of a set and a decision for a solution



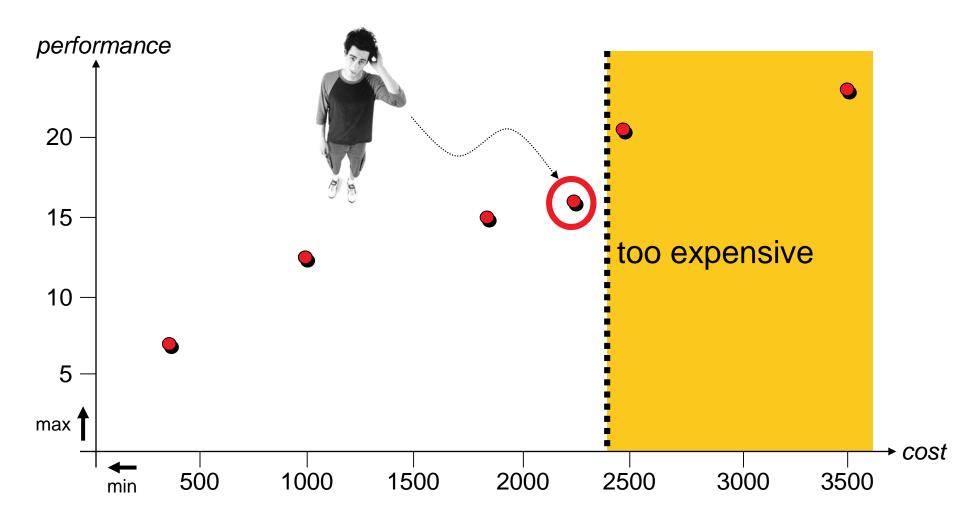
Selecting a Solution: Examples

Possible • ranking: performance more important than cost Approaches:

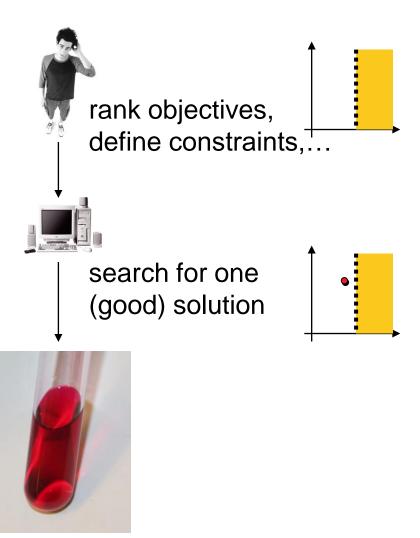


Selecting a Solution: Examples

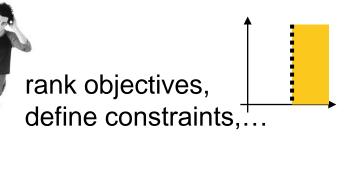
Possible • ranking: performance more important than cost Approaches: 2 constraints: cost must not exceed 2400



Before Optimization:

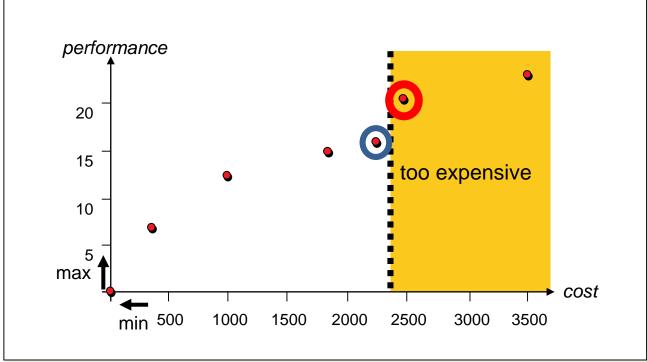


Before Optimization:

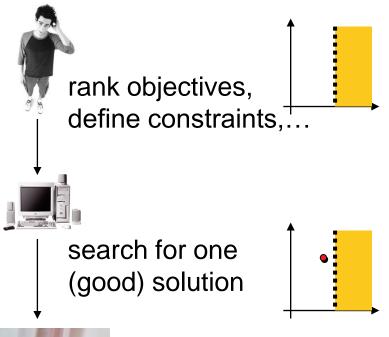


search for one (good) solution



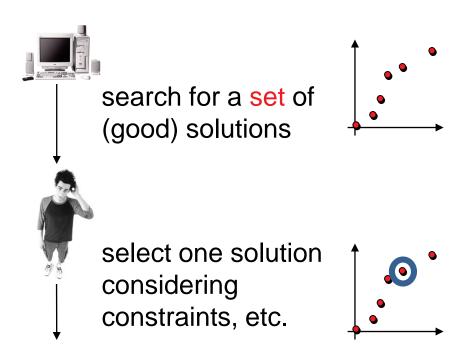


Before Optimization:





After Optimization:



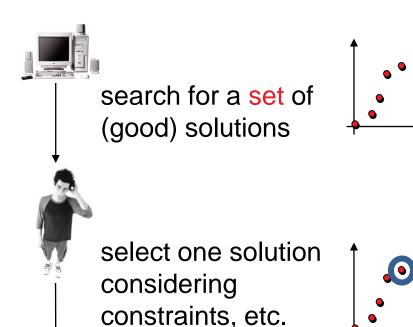


Before Optimization:

rank objectives, define constraints,...

(good) solution

After Optimization:

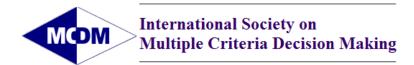




Focus: learning about a problem

- trade-off surface
- interactions among criteria
- structural information
- also: interactive optimization

Two Communities...





- established field (beginning in 1950s/1960s)
- bi-annual conferences since1975
- background in economics, math, management and social sciences
- focus on optimization and decision making

- quite young field (first papers in mid 1980s)
- bi-annual conference since 2001
- background in computer science, applied math and engineering
- focus on optimization algorithms

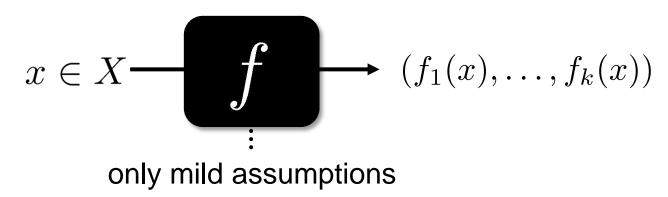
...Slowly Merge Into One



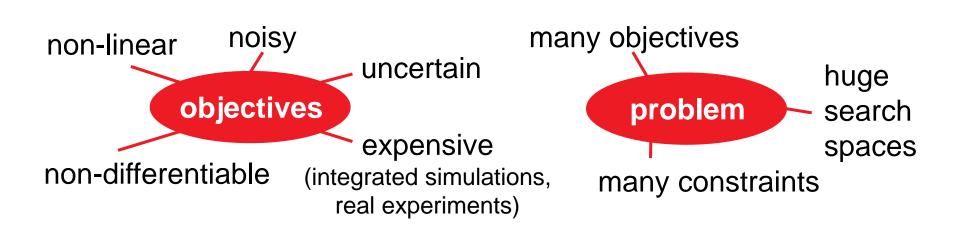
- MCDM track at EMO conference since 2009
- special sessions on EMO at the MCDM conference since 2008
- joint Dagstuhl seminars since 2004

One of the Main Differences

Blackbox optimization



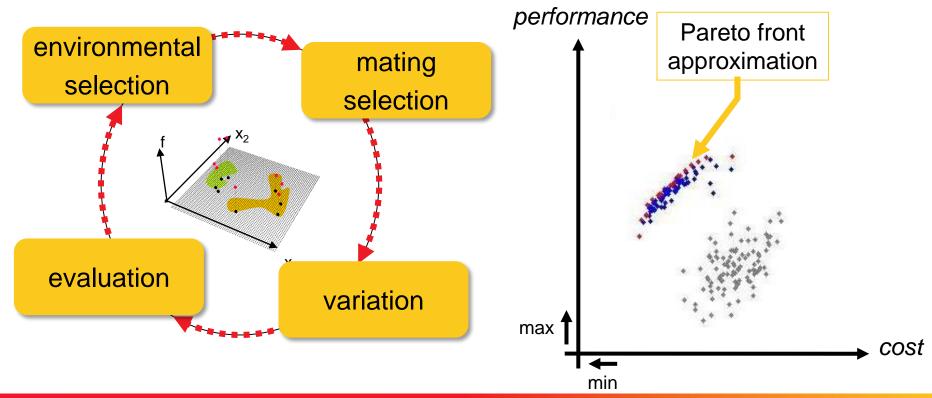
→ EMO therefore well-suited for real-world engineering problems



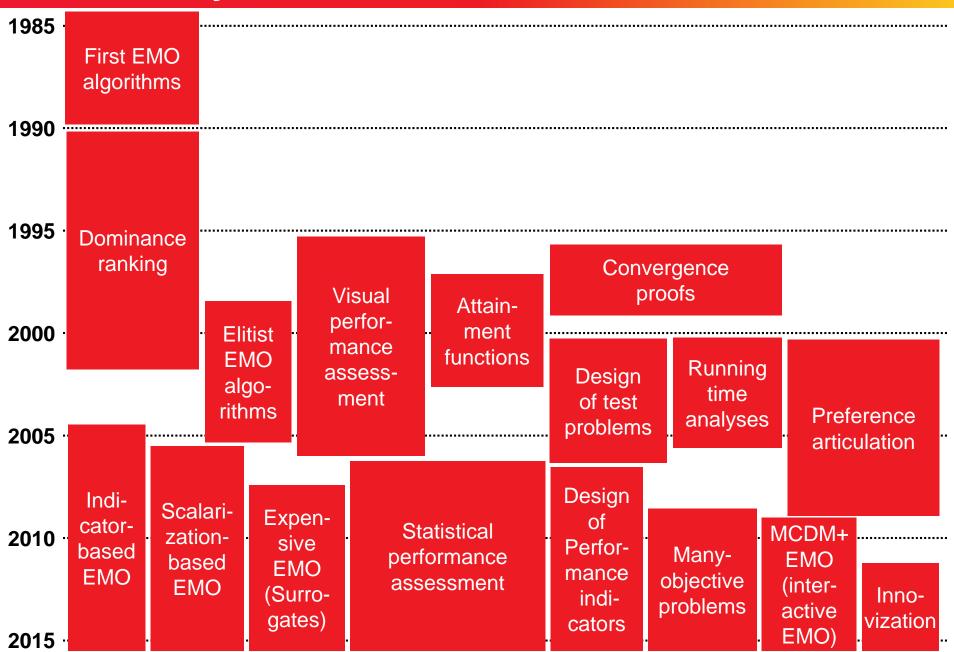
The Other Main Difference

Evolutionary Multiobjective Optimization

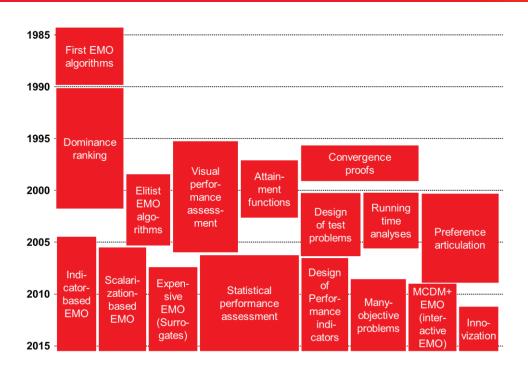
- set-based algorithms
- therefore possible to approximate the Pareto front in one run

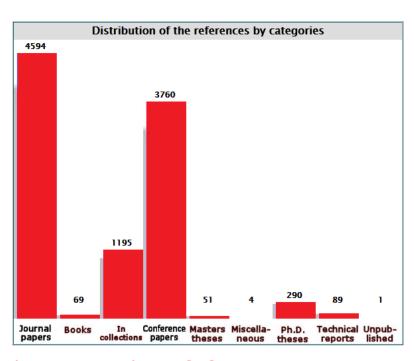


The History of EMO At A Glance

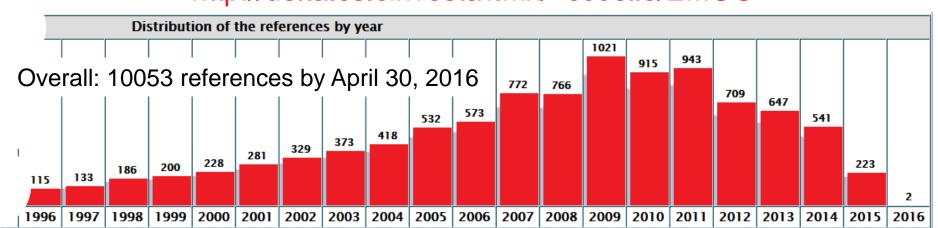


The History of EMO At A Glance





http://delta.cs.cinvestav.mx/~ccoello/EMOO



The EMO Community



Overview

The Big Picture

Algorithm Design Principles and Concepts

Performance Assessment

Fitness Assignment: Principal Approaches

aggregation-based

problem decomposition (multiple single-objective optimization problems)

scaling-dependent

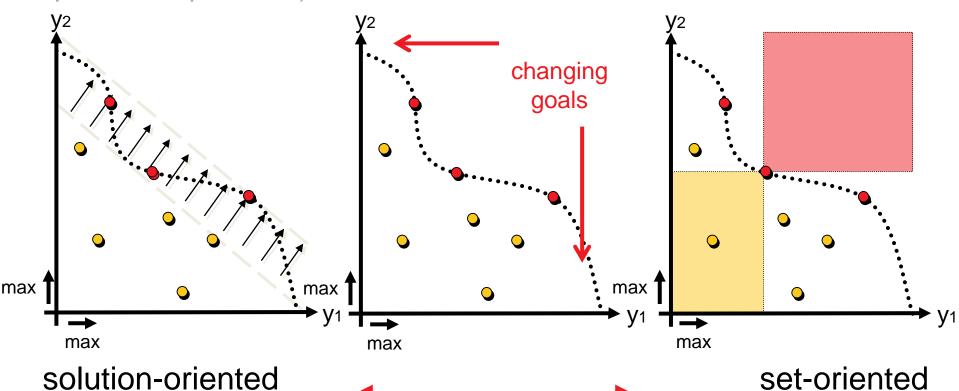
criterion-based

VEGA

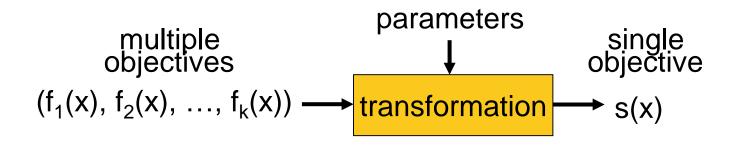
dominance-based

SPEA2, NSGA-II "modern" EMOA

scaling-independent

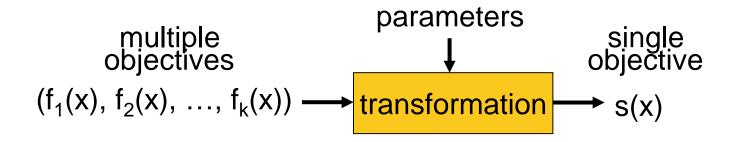


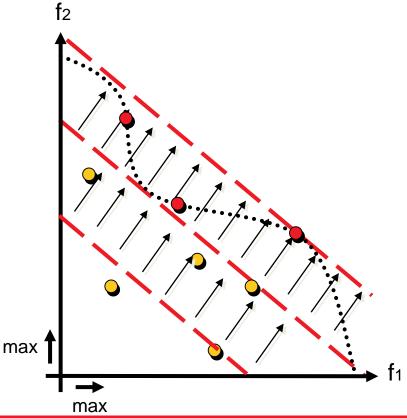
Solution-Oriented Problem Transformations



A scalarizing function s is a function $s:Z\to\mathbb{R}$ that maps each objective vector $u=(u_1,\ldots,u_n)\in Z$ to a real value $s(u)\in\mathbb{R}$

Solution-Oriented Problem Transformations





Example 1: weighted sum approach

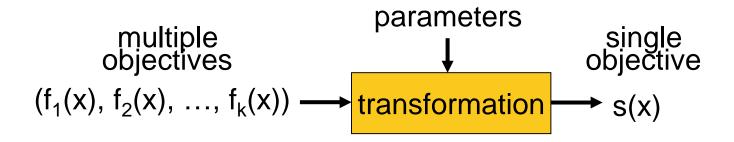
$$(w_1, w_2, ..., w_k)$$

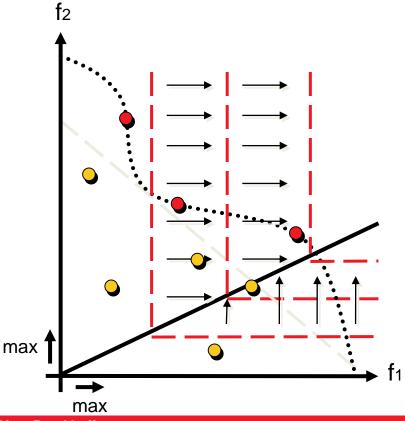
$$\downarrow$$

$$y = w_1y_1 + ... + w_ky_k$$

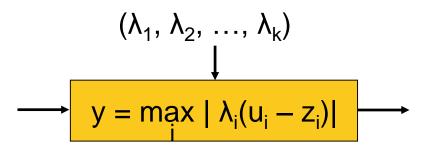
Disadvantage: not all Paretooptimal solutions can be found if the front is not convex

Solution-Oriented Problem Transformations



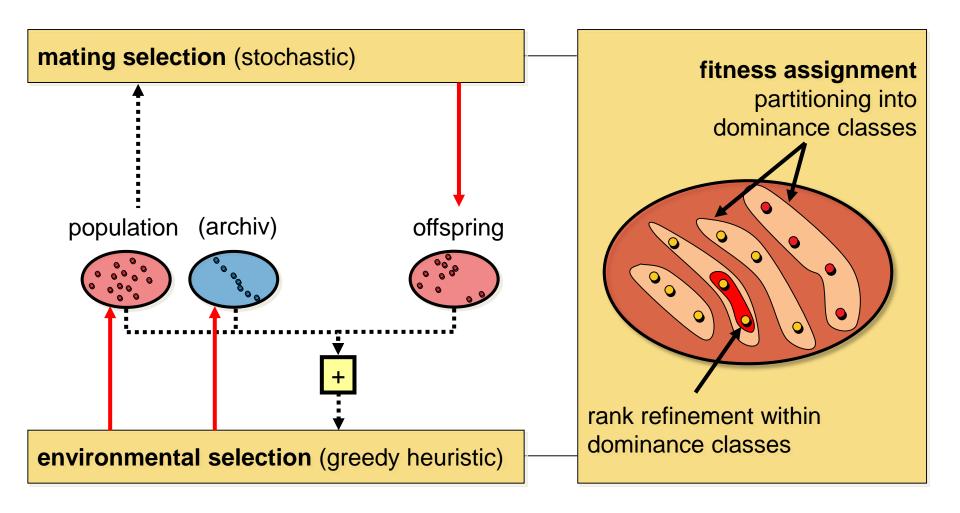


Example 2: weighted Tchebycheff



Several other scalarizing functions are known, see e.g. [Miettinen 1999]

General Scheme of Most Set-Oriented EMO



Ranking of the Population Using Dominance

- ... goes back to a proposal by David Goldberg in 1989.
- ... is based on pairwise comparisons of the individuals only.
- dominance rank: by how many individuals is an individual dominated? MOGA, NPGA
- dominance count: how many individuals does an individual dominate? SPEA, SPEA2
- dominance depth: at which front is an individual located? NSGA, NSGA-II, most of the recently proposed algorithms

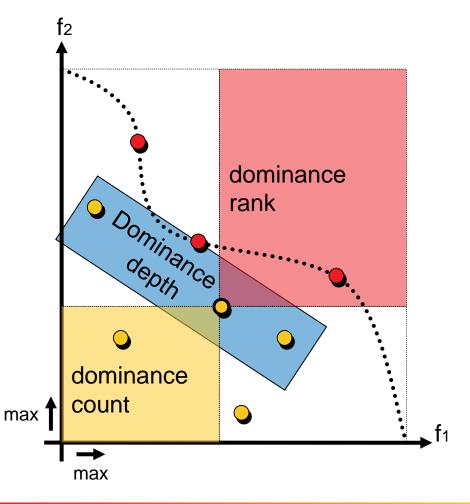
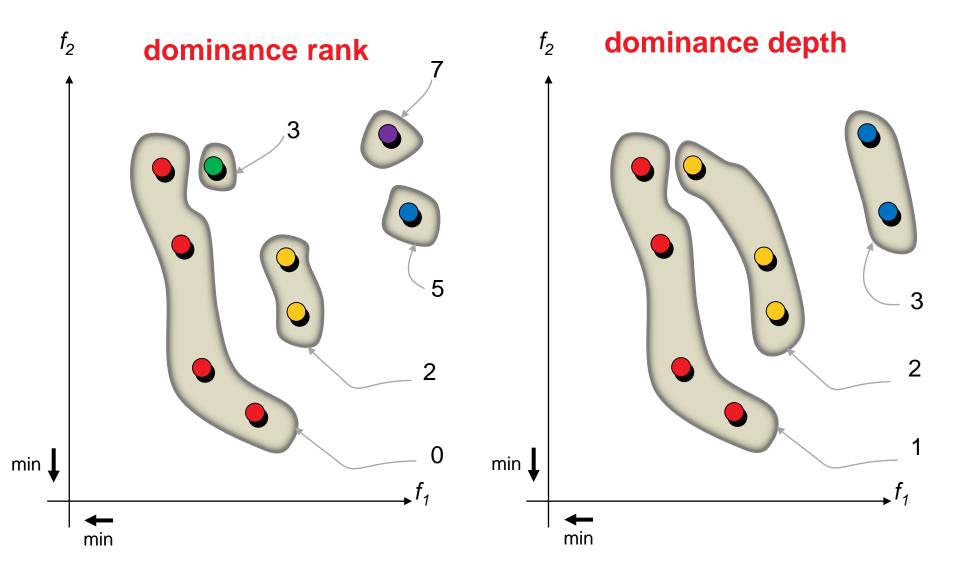


Illustration of Dominance-Based Partitioning



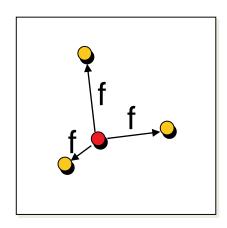
Refinement of Dominance Rankings

Goal: rank incomparable solutions within a dominance class

Diversity information

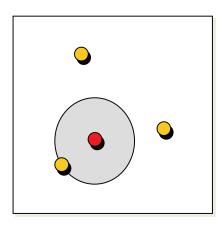
Kernel method

diversity = function of the distances



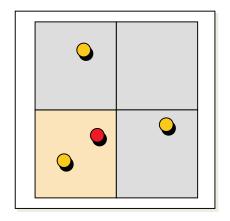
k-th nearest neighbor

diversity =
function of distance
to k-th nearest neighbor



Histogram method

diversity =
number of elements
 within box(es)

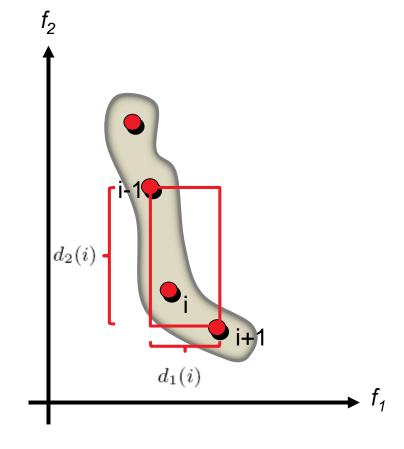


(Contribution to a) quality indicator

Example: NSGA-II Diversity Preservation

Crowding Distance (CD)

- sort solutions with regard to each objective
- assign CD maximum value to extremal objective vectors
- compute CD based on the distance to the neighbors in each objective



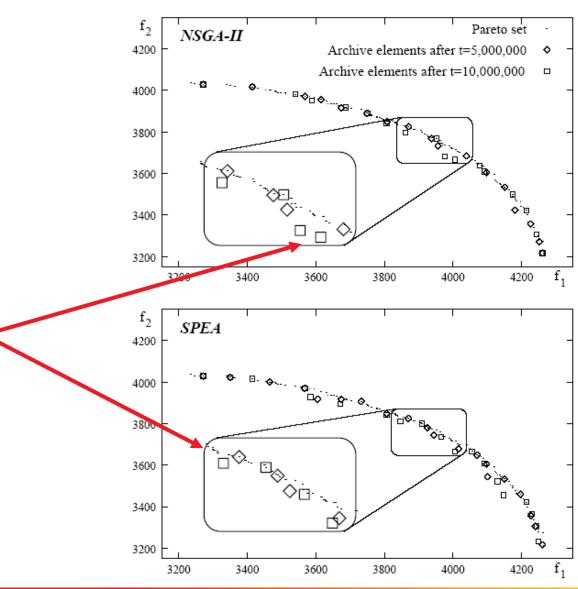
$$CD(i) = \frac{d_1(i)}{f_{1,\text{max}} - f_{1,\text{min}}} + \dots + \frac{d_m(i)}{f_{m,\text{max}} - f_{m,\text{min}}}$$

SPEA2 and NSGA-II: Deteriorative Cycles

Selection in SPEA2 and NSGA-II can result in

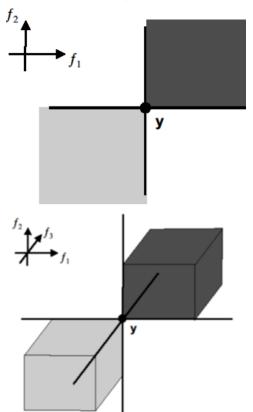
deteriorative cycles

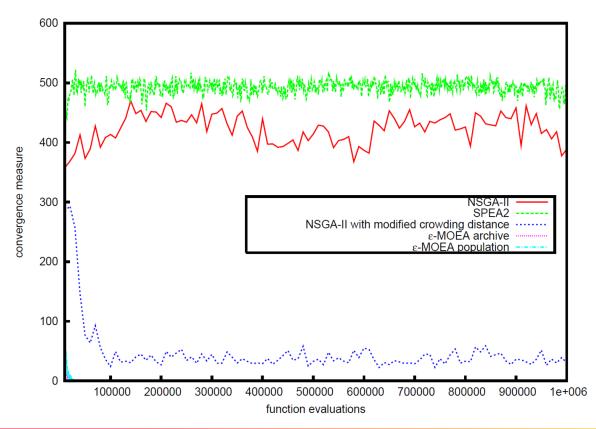
non-dominated solutions already found can be lost



Remark: Many-Objective Optimization

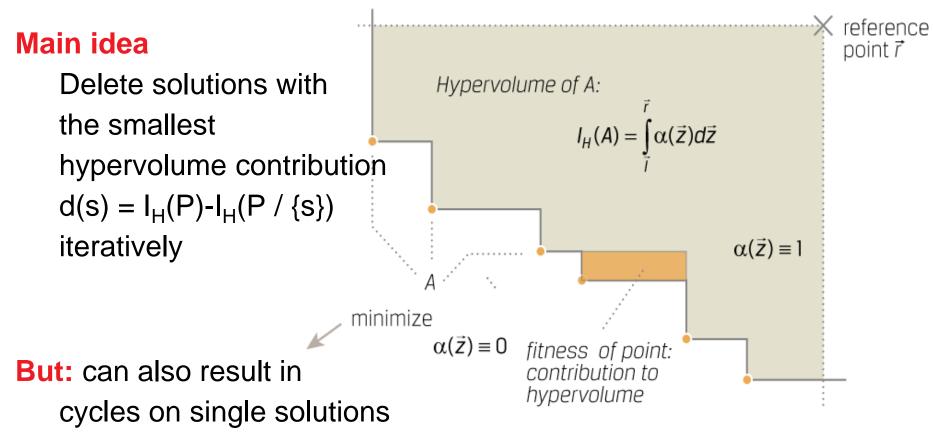
- high number of objectives
 - → percentage of non-dominated solutions within a random sample quickly approaches 100 %
 - > optimization is mainly guided by diversity criterion
 - → apply secondary criterion compliant with dominance relation





Hypervolume-Based Selection

Latest Approach (SMS-EMOA, MO-CMA-ES, HypE, ...) use hypervolume indicator to guide the search: refines dominance



[Judt et al. 2011], [López-Ibáñez et al. 2011]

and is expensive to compute exactly for many objectives

[Bringmann and Friedrich 2009]

Indicator-Based Selection

Concept can be generalized to any quality indicator

A (unary) quality indicator I is a function $I: \Psi = 2^X \mapsto \mathbb{R}$ that assigns a Pareto set approximation a real value.

Multiobjective Indicator Single-objective Problem

- for example: R2-indicator [Brockhoff et al. 2012], [Trautmann et al. 2013],
 [Díaz-Manríquez et al. 2013]
- Generalizable also to contribution to larger sets
 HypE [Bader and Zitzler 2011]: Hypervolume sampling + contribution if more than 1 (random) solution deleted

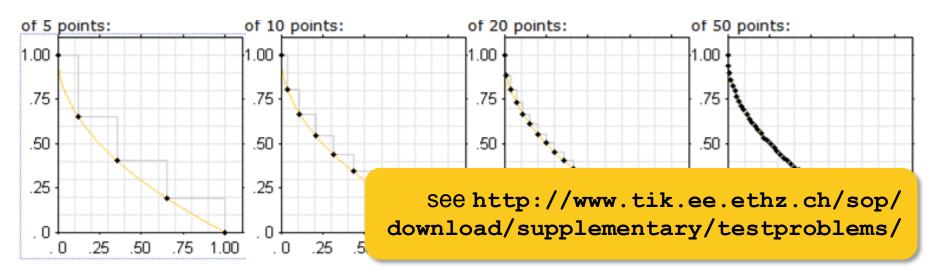
The Optimization Goal in Indicator-Based EMO

When the goal is to maximize a unary indicator...

- we have a single-objective problem on sets
- but what is the optimum?
- important: population size μ plays a role!

Optimal µ-Distribution:

A set of μ solutions that maximizes a certain unary indicator I among all sets of μ solutions is called optimal μ -distribution for I. [Auger et al. 2009a]



Optimal µ-Distributions for the Hypervolume

Hypervolume indicator refines dominance relation

 \Rightarrow most results on optimal μ -distributions for hypervolume

Optimal µ-Distributions (example results)

[Auger et al. 2009a]:

- contain equally spaced points iff front is linear
- density of points $\propto \sqrt{-f'(x)}$ with f' the slope of the front

[Friedrich et al. 2011]:

optimal μ-distributions for the hypervolume correspond to ε-approximations of the front

OPT
$$1 + \frac{\log(\min\{A/a, B/b\})}{n}$$
 HYP
$$1 + \frac{\sqrt{A/a} + \sqrt{B/b}}{n - 4}$$
 logHYP
$$1 + \frac{\sqrt{\log(A/a)\log(B/b)}}{n - 2}$$

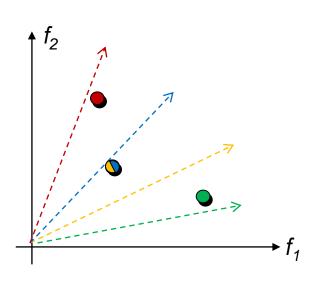
(probably) does not hold for > 2 objectives

Decomposition-Based Selection: MOEA/D

MOEA/D: Multiobjective Evolutionary Algorithm Based on Decomposition [Zhang and Li 2007]

Ideas:

- optimize N scalarizing functions in parallel
- use best solutions of neighbor subproblems for mating
- keep the best solution for each scalarizing function
- update neighbors
- use external archive for non-dominated solutions
- several variants and enhancements



Remark: Variation in EMO

- at first sight not different from single-objective optimization
- most research on selection mechanisms (until now)
- but: convergence to a set ≠ convergence to a point

Open Question:

how to achieve fast convergence to a set?

Related work:

- set-based gradient of the HV [Emmerich et al. 2007]
- multiobjective CMA-ES [Igel et al. 2007] [Voß et al. 2010]
- RM-MEDA [Zhang et al. 2008]
- set-based variation [Bader et al. 2009]
- set-based fitness landscapes [Verel et al. 2011]
- offline and online configuration based on libraries of variation operators [Bezerra et al. 2015] [Hadka and Reed 2013]

Overview

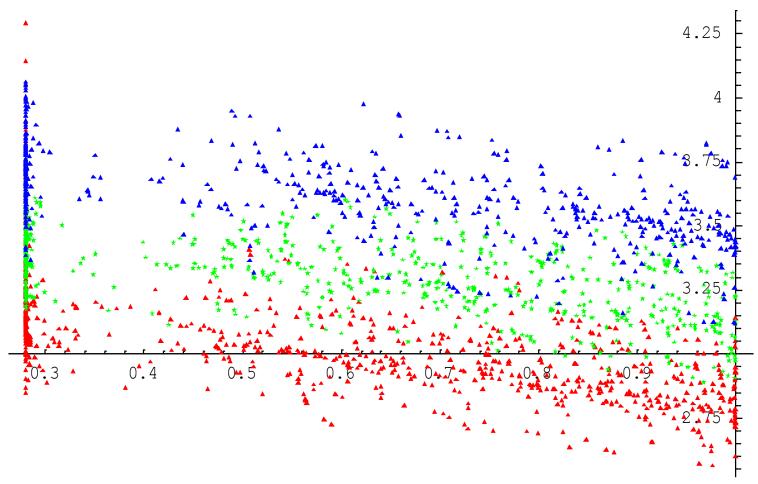
The Big Picture

Algorithm Design Principles and Concepts

Performance Assessment

Once Upon a Time...

... multiobjective EAs were mainly compared visually:



ZDT6 benchmark problem: IBEA, SPEA2, NSGA-II

Two Approaches for Empirical Studies

Attainment function approach

- applies statistical tests directly to the approximation set
- detailed information about how and where performance differences occur

A attains B attains grand worst attainment surface grand best attainment minimize minimize

Quality indicator approach

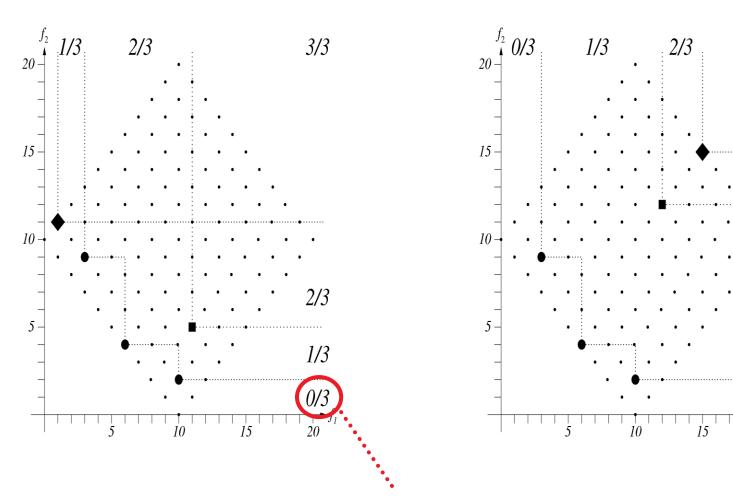
- reduces each approximation set to a single quality value
- applies statistical tests to the quality values

Indicator	A	В
Hypervolume indicator	6.3431	7.1924
$\epsilon ext{-indicator}$	1.2090	0.12722
R_2 indicator	0.2434	0.1643
R_3 indicator	0.6454	0.3475

see e.g. [Zitzler et al. 2003]

Empirical Attainment Functions

three runs of two multiobjective optimizers

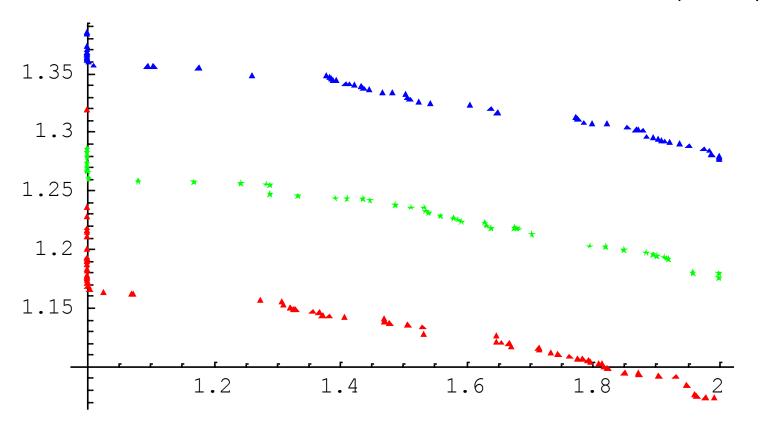


frequency of attaining regions

3/3

Attainment Plots

50% attainment surface for IBEA, SPEA2, NSGA2 (ZDT6)



latest implementation online at

http://eden.dei.uc.pt/~cmfonsec/software.html

R package: http://lopez-ibanez.eu/eaftools

see also [Fonseca et al. 2011]

Quality Indicator Approach

Idea:

- transfer multiobjective problem into a set problem
- define an objective function ("quality indicator") on sets
- use the resulting total (pre-)order (on the quality values)

Question:

Can any total (pre-)order be used or are there any requirements concerning the resulting preference relation?

⇒ Underlying dominance relation (on sets) should be reflected!

$$A \leq B :\Leftrightarrow \forall_{y \in B} \exists_{x \in A} x \leq_{par} y$$

Refinements and Weak Refinements

Tef
 refines a preference relation
 iff

$$A \preceq B \land B \not\preceq A \Rightarrow A \preceq B \land B \not\preceq A$$
 (better \Rightarrow better)

- ⇒ fulfills requirement
- $\mathbf{2} \overset{\mathrm{ref}}{\preccurlyeq}$ weakly refines a preference relation \preccurlyeq iff

$$A \preceq B \land B \npreceq A \Rightarrow A \stackrel{\text{ref}}{\preceq} B$$
 (better \Rightarrow weakly better)

 \Rightarrow does not fulfill requirement, but $\stackrel{\mathrm{ref}}{\preccurlyeq}$ does not contradict \preccurlyeq

! sought are total refinements... [Zitzler et al. 2010]

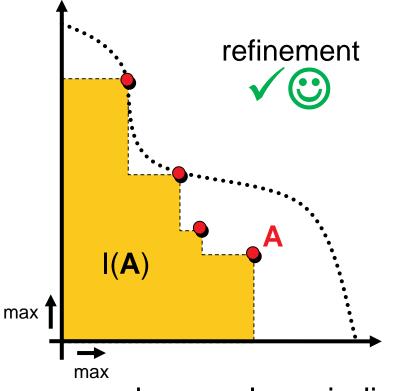
Example: Refinements Using Indicators

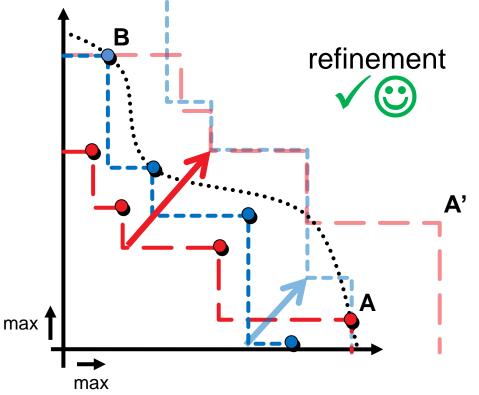
$$A \stackrel{\mathrm{ref}}{\preccurlyeq} B : \Leftrightarrow I(A) \geq I(B)$$

 $A \stackrel{\mathrm{ref}}{\prec} B :\Leftrightarrow I(A,B) \leq I(B,A)$

I(A) = volume of the
weakly dominated area
in objective space

I(A,B) = how much needs A to be moved to weakly dominate B





unary hypervolume indicator

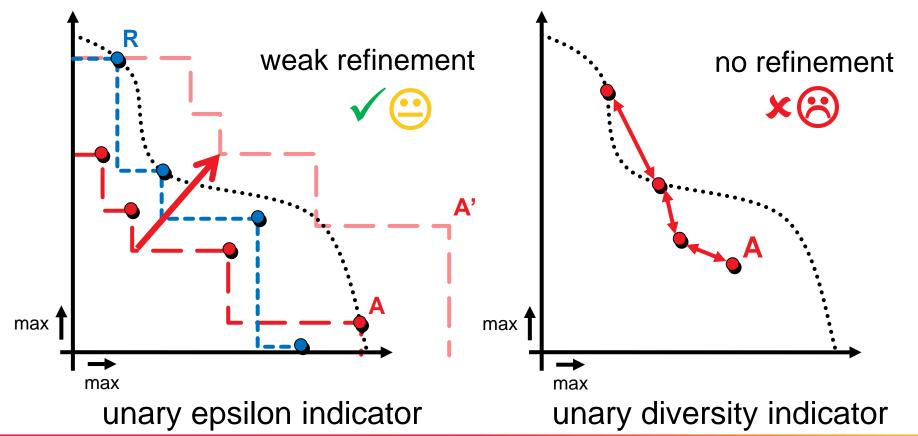
binary epsilon indicator

Example: Weak Refinement / No Refinement

$$A \stackrel{\mathrm{ref}}{\prec} B :\Leftrightarrow I(A,R) \leq I(B,R)$$

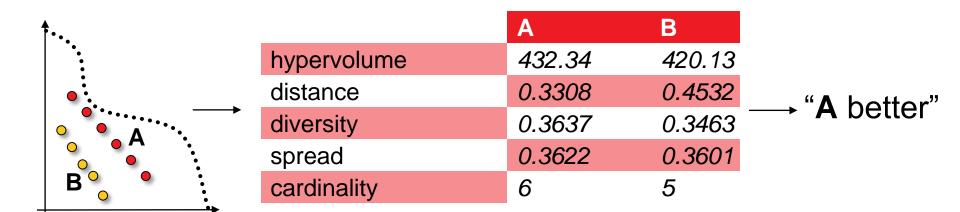
 $A \stackrel{\mathrm{ref}}{\prec} B : \Leftrightarrow I(A) \leq I(B)$

I(A,R) = how much needs A to be moved to weakly dominate R I(A) = variance of pairwise distances



Quality Indicator Approach

Goal: compare two Pareto set approximations A and B



Comparison method C = quality measure(s) + Boolean function

Summary: Quality Indicators

A quality indicator

- maps a solution set to a real number
- can be used with standard performance assessment
 - report median, variance, ...
 - boxplots
 - statistical tests
- should optimally refine the dominance relation on sets

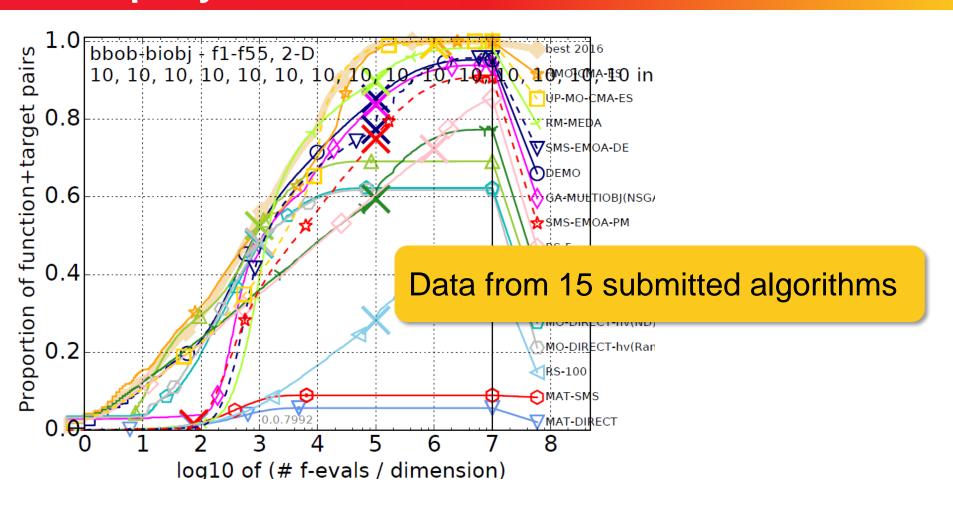
Recommendation:

- use hypervolume (refinement)
- or epsilon indicator or R2 indicator (are weak refinements)

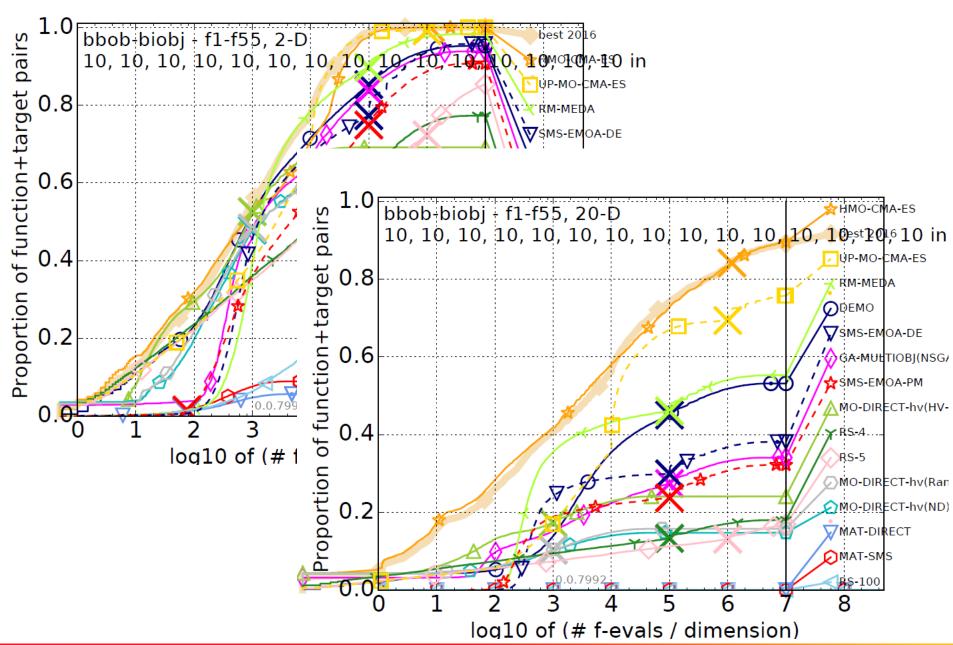
Automated Benchmarking

- State-of-the-art in single-objective optimization: Blackbox
 Optimization Benchmarking (BBOB) with COCO platform
 https://github.com/numbbo/coco
- This year: first release of a bi-objective test suite and corresponding BBOB-2016 workshop @ GECCO
- Focus on target-based runlengths
 - gives (nearly) anytime, interpretable results
 - defines problem=(test function instance, single-objective goal e.g. min. indicator difference to reference set, target precision)
 - reports average runtimes (aRT) to reach target precision
- COCO provides data profiles, scaling plots, scatter plots, tables, statistical tests, etc. automatically

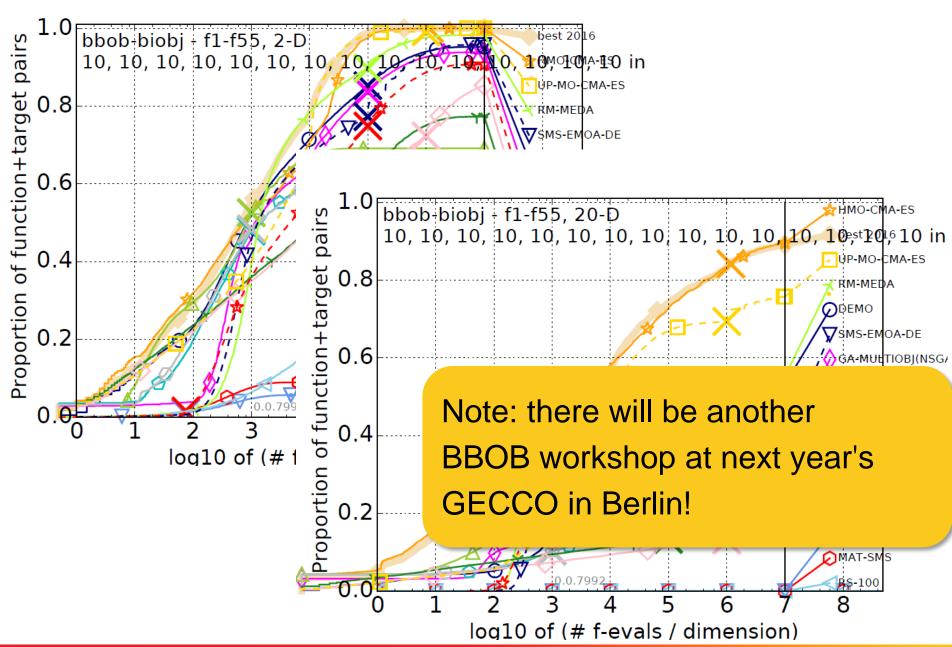
Exemplary BBOB-2016 Results

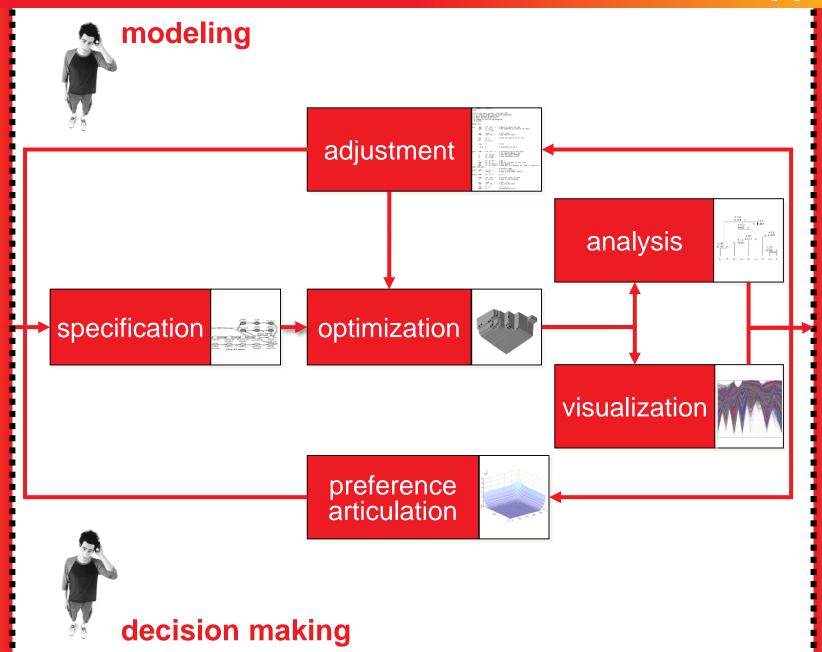


Exemplary BBOB-2016 Results



Exemplary BBOB-2016 Results





problem

The EMO Community

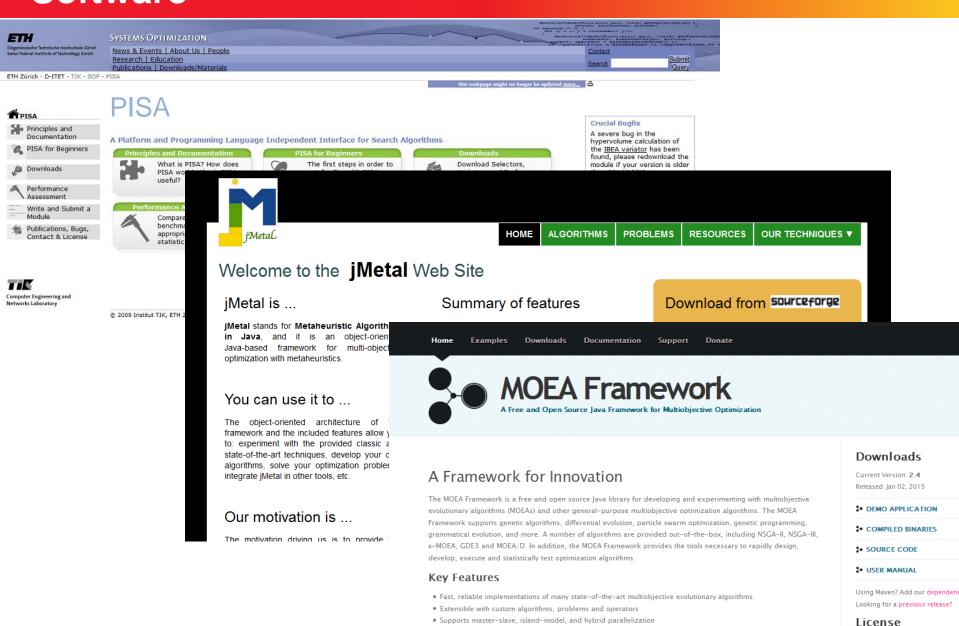
Links:

- EMO mailing list: https://lists.dei.uc.pt/mailman/listinfo/emo-list
- MCDM mailing list: http://lists.jyu.fi/mailman/listinfo/mcdm-discussion
- EMO bibliography: http://www.lania.mx/~ccoello/EMOO/
- EMO conference series: http://www.emo2017.org/

Books:

- Multi-Objective Optimization using Evolutionary Algorithms
 Kalyanmoy Deb, Wiley, 2001
- Evolutionary Algorithms for Solving Multi Evolutionary Algorithms for Solving Multi-Objective Problems Objective Problems, Carlos A. Coello Coello, David A. Van Veldhuizen & Gary B. Lamont, Kluwer, 2nd Ed. 2007
- Multiobjective Optimization—Interactive and Evolutionary
 Approaches, J. Branke, K. Deb, K. Miettinen, and R. Slowinski, editors, volume 5252 of LNCS. Springer, 2008 [(still) many open questions!]
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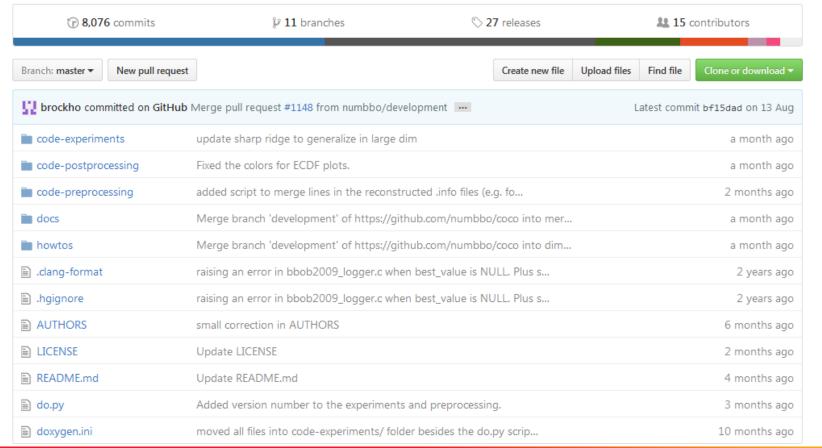
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Perspectives

Challenging Open (Research) Directions

- from algorithms to toolkits
 - libraries of modules for each task (selection, variation, etc.)
 - problem-specific algorithm configuration/ parameter tuning
- benchmarking
 - comparison with classical approaches
 - design/selection of practically relevant problems
 - Algorithm/toolkit recommendations for practice
- integration of EMO and MCDM into one field
- interactive preference articulation and learning
- interactive problem design
- integration of problem-specific knowledge

Questions?

Additional Slides

Instructor Biography: Dimo Brockhoff

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After obtaining his diploma in computer science (Dipl.-Inform.) from University of Dortmund, Germany in 2005, Dimo Brockhoff received his PhD (Dr. sc. ETH) from ETH Zurich, Switzerland in 2009. Between June 2009 and October 2011 he held postdoctoral research positions---first at INRIA Saclay Ile-de-France in Orsay and then at Ecole Polytechnique in Palaiseau, both in France. Since November 2011 he has been a junior researcher (now CR1) at INRIA Lille - Nord Europe in Villeneuve d'Ascq, France. His most recent research interests are focused on evolutionary multiobjective optimization (EMO) and other (single-objective) blackbox optimization techniques, in particular with respect to benchmarking, theoretical aspects, and expensive optimization.

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