# Mathematical modelling for dose deposition in photontherapy

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### Work realized under the supervision of:

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# Context

### In 2012: 14.1 million cancers diagnosed around the world

Types of treatements: radiotherapy, surgery and chemotherapy

Radiations  $\equiv$  beams of particles

Deposited energy (dose)  $\Rightarrow$  Biological effects

### **Objectives:**

Dose computation **fast** and **accurate** 

 $\hookrightarrow \mathsf{Optimization} \ \mathsf{algorithm}$ 



# Available models

Transport of particles:

### Kinetic level

 $\hookrightarrow$  numerically too costly (Monte Carlo, DOM)

### • Angular moment approach

 $\hookrightarrow \mathsf{good}\ \mathsf{compromise}$ 

### • Hydrodynamic level

 $\hookrightarrow$  unsufficient for the present medical applications

# Present work

### Kinetic model:

- Modelling
- Conservation properties
- Well-posedness

### Moment model:

- Modelling
- Domain of validity
- Computation of closures

### Numerical schemes:

- Non-linear equations
- Fast characteristics problem

### **Optimization algorithm:**

• Projected gradient algorithm

### Main difficulties:

- Numerical computations of moment closures
- Time-efficient schemes in low density media

### 1 State-of-the-art

### 2 Moment models

- Principle
- Realizability domain
- The closure problem

### 3 Numerical approaches

- Spatial discretization: Relaxation method
- Energy discretization: An explicit scheme
- Energy discretization: An implicit scheme

# 1 State-of-the-art

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# Kinetic equations

### Fluence

 $dN = \psi(\epsilon, x, \Omega) d\epsilon dx d\Omega \geq 0$ 

Energy  $\epsilon \in [\epsilon_{\min}, \epsilon_{\max}]$ , Position  $x \in Z$ , Direction of flight  $\Omega \in S^2$ 

### **Kinetic equations**

$$\begin{split} \Omega.\nabla_{x}\psi_{\gamma} &= \rho\left(Q_{\gamma\to\gamma}(\psi_{\gamma})+Q_{e\to\gamma}(\psi_{e})\right),\\ \Omega.\nabla_{x}\psi_{e} &= \rho\left(Q_{e\to e}(\psi_{e})+Q_{\gamma\to e}(\psi_{\gamma})\right), \end{split}$$

Relative density  $\rho \in [10^{-3}, 2]$ 



# Kinetic equations



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# Kinetic model

### **Kinetic equations**

$$\Omega.\nabla_{x}\psi_{\gamma} = \rho \qquad (G_{\gamma \to \gamma} - P_{\gamma})(\psi_{\gamma}),$$
  
$$\underbrace{\Omega.\nabla_{x}\psi_{e}}_{\text{transport}} = \rho \left[ \underbrace{\partial_{\epsilon}(S\psi_{e})}_{\text{CSDA}} + \underbrace{(G_{e \to e} - P_{e})(\psi_{e})}_{\text{linear Boltzmann}} + \underbrace{G_{\gamma \to e}(\psi_{\gamma})}_{\text{coupling}} \right],$$

Dose: energy transfered per mass unit

$$D(x) = \int_{\epsilon_{min}}^{\epsilon_{max}} \int_{S^2} \epsilon \left[ Q_{\gamma \to \gamma}(\psi_{\gamma}) + Q_{\gamma \to e}(\psi_{\gamma}) + Q_{e \to e}(\psi_{e}) \right](\epsilon, x, \Omega) d\Omega d\epsilon$$

Principle Realizability domain The closure problem



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# Moments

### Aim: reduce computation costs

### Moment methods:



$$\begin{array}{lll} \textbf{Tensorial notation} & \psi^{i}(\epsilon, x) = & \displaystyle \int_{\Omega \in S^{2}} \underbrace{\Omega \otimes \cdots \otimes \Omega}_{\text{$i$ times}} \psi(\epsilon, x, \Omega) d\Omega, \\ & \psi^{0} & \rightarrow & \text{density} \\ & \psi^{1} & \rightarrow & \text{flux} \\ & \psi^{2} & \rightarrow & \text{pressure} \end{array}$$
$$\textbf{Vectorial notation} & \psi(\epsilon, x) = & \displaystyle \int_{\Omega \in S^{2}} \textbf{m}(\Omega) \psi(\epsilon, x, \Omega) d\Omega, \end{array}$$

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# First order equations

### Orders 0 and 1

$$\begin{array}{ll} \gamma & \left\{ \begin{array}{ll} \nabla_{x}.\psi_{\gamma}^{1} = & \rho(G_{\gamma \to \gamma}^{0} - P_{\gamma}^{0})(\psi_{\gamma}^{0}) \\ \nabla_{x}.\psi_{\gamma}^{2} = & \rho(G_{\gamma \to \gamma}^{1} - P_{\gamma}^{1})(\psi_{\gamma}^{1}) \end{array} \right. \\ e_{-} & \left\{ \begin{array}{ll} \nabla_{x}.\psi_{e}^{1} = & \rho\left[\partial_{\epsilon}(S\psi_{e}^{0}) + (G_{e \to e}^{0} - P_{e}^{0})(\psi_{e}^{0}) + G_{\gamma \to e}^{0}(\psi_{\gamma}^{0})\right] \\ \nabla_{x}.\psi_{e}^{2} = & \rho\left[\partial_{\epsilon}(S\psi_{e}^{1}) + (G_{e \to e}^{1} - P_{e}^{1})(\psi_{e}^{1}) + G_{\gamma \to e}^{1}(\psi_{\gamma}^{1})\right] \end{array} \right. \end{array}$$

 $\hookrightarrow \text{ requires a closure}$ 

$$\psi_{\gamma}^2 = f_{\gamma}(\psi_{\gamma}^0, \psi_{\gamma}^1), \quad \psi_e^2 = f_e(\psi_e^0, \psi_e^1)$$

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# Second order model

### Order 2

$$\begin{aligned} \gamma & \left\{ \begin{array}{ll} \nabla_x . \psi_{\gamma}^3 = & \rho (G_{\gamma \to \gamma}^2 - P_{\gamma}^2) (\psi_{\gamma}^2) \\ e & \left\{ \begin{array}{ll} \nabla_x . \psi_e^3 = & \rho \left[ \partial_\epsilon (S\psi_e^2) + (G_{e \to e}^2 - P_e^2) (\psi_e^2) + (G_{\gamma \to e}^2) (\psi_{\gamma}^2) \right] \end{array} \right. \end{aligned}$$

 $\hookrightarrow \textbf{requires a closure}$ 

$$\psi_{\gamma}^3 = g_{\gamma}(\psi_{\gamma}^1,\psi_{\gamma}^2), \quad \psi_e^3 = g_e(\psi_e^1,\psi_e^2)$$

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# General notation

### **Rewritten equation**

$$\nabla_{\mathbf{x}}.\mathbf{F} = \rho \mathbf{Q}(\boldsymbol{\psi}),$$

$$egin{aligned} \psi &= (\psi_\gamma, \ \psi_e), \qquad F = (F_\gamma, \ F_e), \ & \mathbf{Q}(\psi) &= \left( (\mathbf{G}_{\gamma o \gamma} - \mathbf{P}_\gamma)(\psi_\gamma), \quad \partial_\epsilon(S\psi_e) + (\mathbf{G}_{e o e} - \mathbf{P}_e)(\psi_e) + \mathbf{G}_{\gamma o e}(\psi_\gamma) 
ight), \end{aligned}$$

for 
$$\alpha = \gamma, e$$
  
 $\psi_{\alpha} \equiv \int_{S^2} \mathbf{m}(\Omega) \psi_{\alpha}(\Omega) d\Omega, \quad F_{\alpha} \equiv \int_{S^2} \Omega \otimes \mathbf{m}(\Omega) \psi_{\alpha}(\Omega) d\Omega$   
 $\hookrightarrow$  requires a closure  $F_{\gamma}(\psi_{\gamma}) \quad F_{e}(\psi_{e})$ 



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Principle Realizability domain The closure problem

# Common construction of the closure

### Moments

 $\psi$ 

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# Common construction of the closure

Moments	$\rightarrow$	Ansatz
$oldsymbol{\psi}$	$\rightarrow$	$\psi_R(\Omega)$

$$\mathcal{C}(\boldsymbol{\psi}) = \left\{ \psi \quad , \quad \int_{S^2} \mathbf{m}(\Omega) \psi(\Omega) d\Omega = \boldsymbol{\psi} \right\} \quad ,$$

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# Common construction of the closure

$$\mathcal{C}(\psi) = \left\{\psi \quad , \quad \int_{S^2} \mathbf{m}(\Omega)\psi(\Omega)d\Omega = \psi\right\} \quad ,$$

Principle Realizability domain The closure problem

# Common construction of the closure

$$\mathcal{C}(\psi) = \left\{ \psi \geq 0, \quad \int_{S^2} \mathbf{m}(\Omega) \psi(\Omega) d\Omega = \psi \right\} ,$$

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# Common construction of the closure

$$\mathcal{C}(\psi) = \left\{\psi \ge 0, \quad \int_{S^2} \mathbf{m}(\Omega)\psi(\Omega)d\Omega = \psi\right\} \ne \emptyset,$$

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# Common construction of the closure

Ansatz  $\psi_R$  in

$$\mathcal{C}(\boldsymbol{\psi}) = \left\{ \psi \geq \mathbf{0}, \quad \int_{S^2} \mathbf{m}(\Omega) \psi(\Omega) d\Omega = \boldsymbol{\psi} \right\} \neq \emptyset,$$

**Realizability domain** 

$$\mathcal{R}_{\mathbf{m}} = \left\{ \boldsymbol{\psi} \in \mathbb{R}^{Card(\mathbf{m})}, \quad \text{s.t.} \\ \exists \psi \in L^{1}(S^{2}), \quad \psi \geq 0, \quad \boldsymbol{\psi} = \int_{S^{2}} \mathbf{m}(\Omega) \psi(\Omega) d\Omega \right\}$$

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# Properties of the realizability domain

### Proposition

 $\mathcal{R}_m$  is an open convex cone

 $\forall \quad \alpha_1 > 0, \ \alpha_2 > 0, \quad \psi_1 \in \mathcal{R}_{\mathsf{m}}, \ \psi_2 \in \mathcal{R}_{\mathsf{m}}, \qquad \alpha_1 \psi_1 + \alpha_2 \psi_2 \in \mathcal{R}_{\mathsf{m}}$ 

 $\hookrightarrow$  construction of numerical schemes

### Proposition

If  $\psi \in \partial \mathcal{R}_{\mathbf{m}}$ , then there exists a measure  $\gamma$ s.t.  $\psi = \int_{\mathbb{C}^2} \mathbf{m}(\Omega) d\gamma(\Omega)$ 



 $\hookrightarrow$  computation of the closure

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# Characterization of the realizability domain<sup>2,3</sup>

### Proposition (First order moments)

Choose  $\mathbf{m}(\Omega) = (1, \Omega)$ , then

$$\mathcal{R}_{\mathbf{m}} = \left\{ \boldsymbol{\psi} \in \mathbb{R}^{4}, \quad s.t. \quad |\psi^{1}| < \psi^{0} \right\} \cup \left\{ \mathbf{0}_{\mathbb{R}^{4}} \right\}$$

If  $|\psi^1| = \psi^0$ , then  $\gamma = \psi^0 \delta \left( \Omega - rac{\psi^1}{\psi^0} 
ight)$ 

### Proposition (Second order moments)

Choose  $\textbf{m}(\Omega)=(\Omega_1,~\Omega_2,~\Omega_3,~\Omega_1^2,~\Omega_2^2,~\Omega_3^2,~\Omega_1\Omega_2,~\Omega_1\Omega_3,~\Omega_2\Omega_3),$  then

$$\begin{aligned} \mathcal{R}_{\mathbf{m}} &= \left\{ \boldsymbol{\psi} \in \mathbb{R}^{9}, \quad s.t. \quad |\boldsymbol{\psi}^{1}| < tr(\boldsymbol{\psi}^{2}), \\ & tr(\boldsymbol{\psi}^{2})\boldsymbol{\psi}^{2} - \boldsymbol{\psi}^{1}\otimes\boldsymbol{\psi}^{1} > 0 \right\} \cup \{\boldsymbol{0}_{\mathbb{R}^{9}}\} \end{aligned}$$

<sup>2</sup>Kershaw, 1976

<sup>3</sup>Akhiezer, 1962

Principle Realizability domain The closure problem



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Principle Realizability domain The closure problem

# $M_1$ closure

Ansatz  $\psi_{M_1}$  in

$$\mathcal{C}_1 = \left\{ \psi \ge 0, \quad \int_{S^2} \psi d\Omega = \psi^0, \quad \int_{S^2} \Omega \psi d\Omega = \psi^1 \right\} \neq \emptyset \text{ if } \psi \in \mathcal{R}_m,$$

Choice of the ansatz<sup>4,5</sup>

 $\psi_{M_1} = \operatorname*{argmin}_{\psi \in \mathcal{C}_1} (\mathcal{H}(\psi)) \quad \Rightarrow \quad \psi_{M_1} = \exp{(S + V.\Omega)},$ 

<sup>4</sup>Minerbo, *J. Quant. Spect. Rad. Transfer*, 1977 <sup>5</sup>Levermore, *J. Stat. Phys.*, 1995

Principle Realizability domain The closure problem

# $M_1$ closure

### $M_1$ closure:

$$\psi_{M_1} = \operatorname*{argmin}_{\psi \in \mathcal{C}_1} (\mathcal{H}(\psi)) = \exp\left(\mathbf{S} + \mathbf{V} \cdot \Omega\right) \quad \rightarrow \quad \psi^2 \approx \int_{S^2} \Omega \otimes \Omega \psi_{M_1} d\Omega.$$

### Advantages:

- Symmetric hyperbolic<sup>5</sup>
- Realizable
- Entropy decay<sup>5</sup>
- Accurately models beams

### Alternative computation:

### Numerical cost:

- minimization problem
- numerical quadrature

$$\psi^2 = \psi^0 \left( \frac{1-\chi}{2} \operatorname{Id} + \frac{3\chi - 1}{2} \frac{\psi^1 \otimes \psi^1}{|\psi^1|^2} \right),$$

where  $\chi$  depends only on  $\frac{|\psi^1|}{\psi^0}$ 

<sup>5</sup>Levermore, J. Stat. Phys., 1995

Principle Realizability domain The closure problem

# $M_2$ closure

$$(\psi^1,\psi^2) \rightarrow \psi_{M_2}(\Omega) \rightarrow \psi^3 \approx \int_{S^2} \Omega \otimes \Omega \otimes \Omega \psi_{M_2}(\Omega) d\Omega$$

Ansatz  $\psi_{M_2}$  in

$$\mathcal{C}_2 = \left\{ \psi \ge 0, \quad \int_{S^2} \Omega \psi d\Omega = \psi^1, \quad \int_{S^2} \Omega \otimes \Omega \psi d\Omega = \psi^2 \right\} \neq \emptyset \text{ if } \psi \in \mathcal{R}_{\mathbf{m}},$$

Choice of the ansatz<sup>4,5</sup>

 $\psi_{M_2} = \operatorname*{argmin}_{\psi \in \mathcal{C}_2} (\mathcal{H}(\psi)) \quad \Rightarrow \quad \psi_{M_2} = \exp{(V \cdot \Omega + M : \Omega \otimes \Omega)},$ 

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Principle Realizability domain The closure problem

# $M_2$ closure

### $M_2$ closure:

$$\psi_{M_2} = \exp\left(\mathcal{V}.\Omega + \mathcal{M}:\Omega\otimes\Omega
ight) \quad o \quad \psi^3 pprox \int_{\mathcal{S}^2}\Omega\otimes\Omega\otimes\Omega\psi_{M_2}d\Omega.$$

### Advantages:

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### Alternative: approximation<sup>6</sup>

 $\hookrightarrow$  Idea: Hierarchy of approximated closure

### Numerical cost:

- minimization problem
- numerical quadrature

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<sup>6</sup>Pichard et al, J. Sci. Comput. (2016)

Principle Realizability domain The closure problem

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 $\hookrightarrow \psi^{3}$  approximated in special cases

$$\psi_{M_2} = \exp(S + V.\Omega)$$

<sup>5</sup>Levermore, *J. Stat. Phys.*, 1995 <sup>6</sup>Pichard et al, *J. Sci. Comput.* (2016)

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#### Mathematical modelling for dose deposition in photontherapy 17 / 40

minimization problem

Numerical cost:

• numerical quadrature

Principle Realizability domain The closure problem

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$$\psi_{M_2} = \exp(S + V.\Omega + \alpha(V.\Omega)^2)$$

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## Numerical cost:

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Principle Realizability domain The closure problem

# $M_2$ closure

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 $\hookrightarrow \psi^3$  approximated in special cases

 $\psi_{M_2} = \exp(V.\Omega + M : \Omega \otimes \Omega)$ 

<sup>5</sup>Levermore, *J. Stat. Phys.*, 1995 <sup>6</sup>Pichard et al, *J. Sci. Comput.* (2016)

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## Numerical cost:

- minimization problem
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Principle Realizability domain The closure problem

### 1D test case: single electron beam



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# 2D test case: double electron beam



Figure : Monte Carlo PENELOPE (left), M<sub>1</sub> (middle), M<sub>2</sub> (right)

Monte Carlo: > 10 h  $M_1$ : 2 min  $M_2$ : 8 min

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Spatial discretization: Relaxation method Energy discretization: An explicit scheme Energy discretization: An implicit scheme

# Position of the problem

Consider

$$\partial_{\mathsf{x}}\mathsf{F}(\psi) = \rho \partial_{\epsilon}(S\psi)$$

HLL type numerical scheme (**backward in**  $\epsilon$ )

$$\frac{1}{\Delta x} \left( \frac{\mathbf{F}_{l+\frac{1}{2}}^{n}}{\rho_{l+\frac{1}{2}}} - \frac{\mathbf{F}_{l-\frac{1}{2}}^{n}}{\rho_{l-\frac{1}{2}}} \right) = \frac{S^{n}\psi^{n} - S^{n+1}\psi^{n+1}}{\Delta\epsilon^{n}}$$
$$\mathbf{F}_{l+\frac{1}{2}}^{n} = \frac{1}{2} \left( \mathbf{F}(\psi_{l}^{n}) + \mathbf{F}(\psi_{l+1}^{n}) - (\psi_{l+1}^{n} - \psi_{l}^{n}) \right)$$

stable under condition

$$\Delta \epsilon^n \leq S^n \Delta x \min \rho$$

very restrictive when  $\rho \ll 1$ 



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# Relaxation approach in $1D^7$

Objective: Handle the non-linearity

**Relaxation directions:** Define scalars  $\lambda_+$ 

 $Sp(\partial_{\psi}\mathsf{F}(\psi)) \subset [\lambda_{-},\lambda_{+}],$ 

### Equilibrium states:

Define vectors  ${\sf M}_\pm(\psi)$ 

$$\boldsymbol{\psi} = \mathbf{M}_+ + \mathbf{M}_-, \qquad \mathbf{F}(\boldsymbol{\psi}) = \lambda_+ \mathbf{M}_+ + \lambda_- \mathbf{M}_-,$$

**Relaxed equations:** 

$$\lambda_{\pm}\partial_{x}\mathbf{f}_{\pm}-
ho\partial_{\epsilon}(S\mathbf{f}_{\pm})=rac{\mathbf{M}_{\pm}-\mathbf{f}_{\pm}}{ au},$$

 $\frac{\text{Moment system}}{^{7}\text{Pichard et al, Commun. Comput. Phys., 2016}}$ 



# Relaxation approach

Theorem (Natalini, Commun. Pur. Appl. Math., 1998)

For scalar equations

$$\psi = \lim_{\tau \to 0} \mathbf{f}_+ + \mathbf{f}_-, \qquad F(\psi) = \lim_{\tau \to 0} \lambda_+ \mathbf{f}_+ + \lambda_- \mathbf{f}_-$$

### Extensions:

- Parabolic equations (Bouchut, Guarguaglini and Natalini, Indiana U. Math. J., 1999; Aregba-Driollet, Natalini and Tang, Math. Comput., 2004)
- Systems (Aregba-Driollet and Natalini, J. Numer. Anal., 2000)

Spatial discretization: Relaxation method Energy discretization: An explicit scheme Energy discretization: An implicit scheme

# Relaxation approach in multi-D<sup>7</sup>

### **Relaxation directions:**

Define vectors  $\lambda_i$ 

$$\forall n \in S^2$$
,  $Sp(\partial_{\psi} \mathbf{F}_{\mathbf{n}}(\psi)) \subset \left[\min_i(\lambda_i.n), \max_i(\lambda_i.n)\right]$ 

### **Equilibrium states:**

Define vectors  $\mathbf{M}_{\mathbf{i}}(\psi)$ 

$$\boldsymbol{\psi} = \sum_{i} \mathbf{M}_{i}, \qquad F(\boldsymbol{\psi}) = \sum_{i} \lambda_{i} \otimes \mathbf{M}_{i},$$

**Relaxed equations:** 

$$\lambda_i \cdot \nabla_{\mathsf{x}} \mathbf{f}_i - \rho \partial_{\epsilon} (S \mathbf{f}_i) = \frac{\mathbf{M}_i - \mathbf{f}_i}{\tau},$$

<sup>7</sup>Pichard et al, Commun. Comput. Phys., 2016

Spatial discretization: Relaxation method Energy discretization: An explicit scheme Energy discretization: An implicit scheme

# Construction of a numerical scheme

• At  $\epsilon^n$ , set

$$\mathbf{f}_{i}^{n}:=\mathbf{M}_{i}\left(\boldsymbol{\psi}^{n}\right)$$

Solve the homogeneous (linear) relaxed equations

$$\lambda_i \cdot \nabla_{\mathsf{x}} \mathbf{f}_i - \rho \mathbf{Q}(\mathbf{f}_i) = 0, \tag{1}$$

Project

$$\psi^{n+1} = \sum_i \mathbf{f}_i^{n+1}$$

Construct inconditionally stable schemes for (1)

Spatial discretization: Relaxation method Energy discretization: An explicit scheme Energy discretization: An implicit scheme

# Example of relaxation parameters

In 1D:

$$\lambda_{-} = -1, \qquad \lambda_{+} = +1, \qquad \mathbf{M}_{\pm} \in \mathcal{R}_{\mathbf{m}}$$

In 3D:



Diagonal: 
$$\lambda_i = \pm 2 \frac{(\mathbf{e}_1 \pm \mathbf{e}_2)}{\sqrt{2}},$$

Star: Cartesian + Diagonal,



$$\mathbf{M}_i \in \mathcal{R}_{\mathbf{m}}$$

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# CFL free scheme: 1D explicit FD scheme

Simplified hyperbolic equation

$$\partial_{\epsilon}f + rac{\lambda_{-}}{
ho(x)}\partial_{x}f = 0,$$

### Method of characteristics



Finite Difference scheme

$$f_l^{n+1} = (1-\alpha) f_{l-k_l+1}^n + \alpha f_{l-k_l}^n.$$

Spatial discretization: Relaxation method Energy discretization: An explicit scheme Energy discretization: An implicit scheme

# CFL free scheme: multi-D explicit FD scheme

### Simplified hyperbolic equation

$$\partial_{\epsilon}f + \frac{\lambda_i}{\rho(x)} \cdot \nabla_x f = 0,$$

### Finite Difference scheme

$$f_{l,m}^{n+1} = \sum_{i=0}^{1} \sum_{j=0}^{1} \alpha_{i,j} f_{l'+i,m'+j}^{n}.$$

### Method of characteristics



Spatial discretization: Relaxation method Energy discretization: An explicit scheme Energy discretization: An implicit scheme

# 1D test case: single electron beam in a heterogeneous medium

**1D medium:** 12 cm  $\rightarrow$  1200 cells composed of slabs of density  $\rho_{air} = 10^{-3}$  and  $\rho_{water} = 1$ 



Figure : Representation of the 1D medium.

### Energy step size:

Coarse: 
$$\Delta \epsilon^n = 0.95 S^n \rho_{water} \Delta x$$
, Fine:  $\Delta \epsilon^n = 0.95 S^n \rho_{air} \Delta x$ 

 $\hookrightarrow$  equivals to HLL type solver

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# 1D test case: single electron beam in a heterogeneous medium



**Kinetic**: 15 min; **Moments**: Fine steps:  $M_1$ : 20 sec,  $M_2$ : 1 min Coarse steps: < 1 sec

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# 2D test case: Dose in a cut of a chest



Figure : Isodose curves

Cartesian	+	fine	$\Delta \epsilon^n$	(left)	:	1 h 20 min
Cartesian	+	coarse	$\Delta \epsilon^n$	(middle left)	:	$20  \sec$
Diagonal	+	coarse	$\Delta \epsilon^n$	(middle right)	:	$22  \sec$
Star	+	$\operatorname{coarse}$	$\Delta \epsilon^n$	(right)	:	$1 \min$

Spatial discretization: Relaxation method Energy discretization: An explicit scheme Energy discretization: An implicit scheme

# 2D test case: Error on the dose



Figure : Error compared to the results with fine  $\Delta \epsilon^n$ 

Cartesian	+	coarse	$\Delta \epsilon^n$	(left)
Diagonal	+	coarse	$\Delta \epsilon^n$	(middle)
Star	+	coarse	$\Delta \epsilon^n$	(right)

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State-of-the-art Spatial discretization: Relaxation method Moment models Energy discretization: An explicit scheme Numerical approaches Energy discretization: An implicit scheme

# Implicit scheme

### Equation

$$\partial_{x} \mathbf{F}(\boldsymbol{\psi}) - \rho \mathbf{Q}(\boldsymbol{\psi}) = 0,$$
$$\mathbf{Q}(\boldsymbol{\psi}) = \int_{\epsilon}^{\epsilon_{\max}} \sigma(\epsilon', \epsilon) \boldsymbol{\psi}(\epsilon') d\epsilon' + \dots$$
(2)

Discretization

$$\frac{1}{\Delta x} \left( \frac{\mathsf{F}_{l+\frac{1}{2}}^{n+1}}{\rho_{l+\frac{1}{2}}} - \frac{\mathsf{F}_{l-\frac{1}{2}}^{n+1}}{\rho_{l-\frac{1}{2}}} \right) - \mathsf{Q}_{l}^{n+1} = 0,$$
$$\mathsf{F}_{l+\frac{1}{2}}^{n+1} = \frac{1}{2} \left( \mathsf{F}(\psi_{l}^{n+1}) + \mathsf{F}(\psi_{l+1}^{n+1}) - (\psi_{l+1}^{n+1} - \psi_{l}^{n+1}) \right)$$

(2) discretized with: Quadrature + ...

$$\mathbf{Q}_{l}^{n+1} = A^{n+1,n+1} \psi_{l}^{n+1} + \underbrace{\sum_{i'=1}^{n} A^{n',n+1} \psi_{l}^{n'}}_{\mathbf{U}_{l}^{n}}$$

,

Spatial discretization: Relaxation method Energy discretization: An explicit scheme Energy discretization: An implicit scheme

# An Implicit numerical scheme

### Discretization

$$\frac{1}{\Delta x} \left( \frac{\mathbf{F}_{l+\frac{1}{2}}^{n+1}}{\rho_{l+\frac{1}{2}}} - \frac{\mathbf{F}_{l-\frac{1}{2}}^{n+1}}{\rho_{l-\frac{1}{2}}} \right) - A^{n+1,n+1} \psi_l^{n+1} = \mathbf{U}_l^n, \tag{3}$$

### Proposition

If for all  $k \ge 0$  and I

$$\psi_l^{n-k} \in \mathcal{R}^2_{\mathbf{m}},$$

then there exists a unique solution

$$\psi_l^{n+1} \in \mathcal{R}^2_{\mathbf{m}}$$
 for all l

to (3).

### $\hookrightarrow \mathsf{contraction}\ \mathsf{method}$

Spatial discretization: Relaxation method Energy discretization: An explicit scheme Energy discretization: An implicit scheme

# 2D test case: single photon beam



Spatial discretization: Relaxation method Energy discretization: An explicit scheme Energy discretization: An implicit scheme

# 2D test case: single photon beam

Constraints:

$$Sp(\partial_{\psi}\mathbf{F}_{\mathbf{n}}(\psi)) \subset \left[\min_{i}(\lambda_{i}.n), \max_{i}(\lambda_{i}.n)\right]$$
 (4)

### **Relaxation parameters:**

Non-modified: 
$$\lambda_i = \pm 2e_i$$
,

Modified: 
$$\lambda_i = \pm |\lambda_i| e_i$$
, s.t. (4)



Spatial discretization: Relaxation method Energy discretization: An explicit scheme Energy discretization: An implicit scheme

## 2D test case: single photon beam



Energy discretization: An implicit scheme

## 2D test case: double photon beam in a chest



Monte Carlo (left)  $M_1$  Non-modified (middle left)  $M_2$  Non-modified (middle right) : 30 min  $M_1$  Modified (right)

- : 14 h
- : 13 min
- $24 \min$

# Conclusion

### Problems

- Computation of the closure
- Numerical scheme with a non-linear term
- Numerical scheme with a stiff term

### Solutions

- Approximation of the closure
- Relaxation method
- Implicit scheme inconditionally stable

# Perspectives

### Numerical scheme

- Higher order method
- Bounding of the eigenvalues of the Jacobian of the  $M_2$  flux

### Physics

- Consider more collision types
- Radiobiology

### Moment problem

- Characterizing realizability
- Construct other closures

### Optimization

Improve algorithm

# Thanks for your attention

# Method of moments

### Astrophysics:

• Chandrasekhar (1944-1960)

### Radiative transfer:

- Minerbo (1977-1978)
- Dubroca, Feugeas (1999)
- Buet, Després (2006)

### Fluid:

- Grad (1949)
- Levermore (1996)

### Plasma physics:

- Mallet, Brull, Dubroca (2014, 2015)
- Guisset, Brull, d'Humières, Dubroca, Tikhonchuk (2016)

### Semi-conductors:

- Anile, Romano (2000)
- Hauck (2006)

### Chemotaxy:

• Borsche, Klar, Pham (2016)

### Radiotherapy:

- Duclous, Dubroca, Frank (2010)
- Olbrant, Frank (2010)
- Present PhD thesis (2016)

### Others:

- Junk (2000)
- Schneider (2004)
- Hauck, Levermore, Tits (2007)
- Alldredge, Hauck, Tits (2012)

2D test case: single photon beam



# 2D test case: single photon beam



Monte Carlo: 14 h;

Non-modified: 50 sec

Modified: 205 sec

# Optimization problem

Objectif: minimize

$$J(\psi,\psi^b) = \|D(\psi) - \bar{D}\|_Z^2 + \alpha \|\psi^b\|_{\partial Z}^2$$

**Direct equations** 

$$\begin{cases} \Omega.\nabla_x\psi = Q(\psi), \\ \psi = \psi^b \text{ on } \Gamma^- \\ \psi(\epsilon = \epsilon_{\max}) = 0 \end{cases}$$

# Optimization procedure

Lagrangian

$$L(\psi^{b},\psi,\lambda,\lambda^{b}) = J(\psi^{b},\psi) - (\psi - \psi^{b},\lambda^{b})_{\Gamma^{-}} - (\Omega.\nabla_{x}\psi - Q(\psi),\lambda)_{Int}$$

Differentiating

$$\begin{aligned} d_{\lambda}L(\psi,\psi^{b},\lambda,\lambda^{b})(h) &= (\Omega.\nabla_{x}\psi-Q(\psi), h)_{Int}, \\ d_{\lambda^{b}}L(\psi,\psi^{b},\lambda,\lambda^{b})(h) &= (\psi-\psi^{b}, h)_{\Gamma^{-}}, \\ d_{\psi}L(\psi,\psi^{b},\lambda,\lambda^{b})(h) &= (-\Omega.\nabla_{x}\lambda-Q^{T}(\lambda)+f(\psi), h)_{Int} \\ &-(\lambda-\lambda^{b}, h)_{\Gamma^{-}}+(\lambda, h)_{\Gamma^{+}}+(g(\lambda),h)_{\epsilon_{\max}}, \\ d_{\psi^{b}}L(\psi,\psi^{b},\lambda,\lambda^{b})(h) &= (\alpha\psi^{b}-\lambda^{b}, h)_{\Gamma^{-}}=d_{\psi^{b}}J(\Xi(\psi^{b}),\psi^{b}), \end{aligned}$$

**Adjoint equation** 

$$\begin{cases} -\Omega.\nabla_x \lambda &= Q^T(\lambda) + f(\psi), \\ \lambda &= 0 \text{ on } \Gamma^+ \\ \lambda(\epsilon = \epsilon_{\min}) &= 0 \end{cases}$$

# Optimization results: 1D



# Optimization results: 2D with $M_1$



# Optimization results: 2D with $M_2$

